## Project 1 - BCJR algorithm

This project report is organized into 3 parts: 1. some details of the implementation of the BCJR algorithm; 2. the result of the computer tests (the main result is in Figure 1); 3. other interesting things, such as the performance of the algorithm when $\sigma^{2}$ is not known precisely.
Let $u(t), \boldsymbol{s}(t), \boldsymbol{x}(t)$, and $\boldsymbol{y}(t)$ be the information bit, state vector, codebits, and the noisy codebits at time $t$. Assume that the total time is $T=k+4(k=1024$ is the number of the information bits and 4 is the number of dummy bits). Let $\boldsymbol{U}, \boldsymbol{X}$ and $\boldsymbol{Y}$ be the information, codeword, and noisy codeword from time 0 to $T-1$.

1. Encoder. The generator matrix is

$$
\begin{equation*}
\left(1, \frac{G_{1}(D)}{G_{2}(D)}\right)=\left(1, \frac{1+D^{4}}{1+D+D^{2}+D^{3}+D^{4}}\right) \tag{1}
\end{equation*}
$$

Then (refer to [Berrou et al., 1993, Fig. 1(b)])

$$
\begin{align*}
\boldsymbol{s}(t+1) & =\boldsymbol{s}(t) \mathcal{A}+u(t) \mathcal{B}  \tag{2}\\
\boldsymbol{x}(t) & =\boldsymbol{s}(t) \mathcal{C}+u(t) \mathcal{D}
\end{align*}
$$

where

$$
\mathcal{A}=\left(\begin{array}{llll}
1 & 1 & 0 & 0 \\
1 & 0 & 1 & 0 \\
1 & 0 & 0 & 1 \\
1 & 0 & 0 & 0
\end{array}\right), \mathcal{B}=\left(\begin{array}{llll}
1 & 0 & 0 & 0
\end{array}\right), \mathcal{C}=\left(\begin{array}{ll}
0 & 1 \\
0 & 1 \\
0 & 1 \\
0 & 0
\end{array}\right), \mathcal{D}=\left(\begin{array}{ll}
1 & 1
\end{array}\right)
$$

We can verify that $G(D)$ is as given in (1). For a more convenient way for programming:

$$
\begin{aligned}
\boldsymbol{s}(t+1) & =\left(s_{1}(t)+s_{2}(t)+s_{3}(t)+s_{4}(t)+u(t), s_{1}(t), s_{2}(t), s_{3}(t)\right) \\
\boldsymbol{x}(t+1) & =\left(u(t), s_{1}(t)+s_{2}(t)+s_{3}(t)+u(t)\right)
\end{aligned}
$$

After the encoding, $x_{i}(t)$ is transformed to $\{-1,+1\}$ by mapping $0 \mapsto+1$ and $1 \mapsto-1$.
2. The trellis. There are $2^{4}=16$ states in every stage of the trellis graph. From (2), two edges exit from each state; and also two edges enter each state, since $\mathcal{A}$ is invertible.
We use $\boldsymbol{s} \stackrel{u / \boldsymbol{x}}{\longmapsto} \boldsymbol{s}^{\prime}$ to denote an edge in the trellis graph, starting from state $\boldsymbol{s}$, accompanied by information bit $u$ and codebits $\boldsymbol{x}$, and ending at state $\boldsymbol{s}^{\prime}$.
3. The weights. The evidence is $\mathcal{E}=\boldsymbol{Y}=\boldsymbol{y}(0) \ldots \boldsymbol{y}(T-1)$. What we want to calculate is

$$
p(u(t)=a \mid \mathcal{E})=\alpha \sum_{\boldsymbol{U}: u(t)=a} p(\boldsymbol{U}) p(\boldsymbol{Y} \mid \boldsymbol{X})=\alpha \sum_{\boldsymbol{U}: u(t)=a} \prod_{i=0}^{T-1} p(u(i)) p(\boldsymbol{y}(i) \mid \boldsymbol{x}(i))
$$

where the notation $\alpha$ is the same as in [McEliece et al., 1998]; or $\alpha=p(\boldsymbol{Y})^{-1}$. (Note that the channel is memoryless.) To apply the BCJR algorithm, we define the weight of an edge $e=\boldsymbol{s} \stackrel{u / \boldsymbol{x}}{\longmapsto} \boldsymbol{s}^{\prime}$ as

$$
w(e)=\pi(u) p(\boldsymbol{y} \mid \boldsymbol{x})
$$

where $\pi(u)$ is the a priori probability that the information bit is $u$.
Since we will use the log-likelihood ratio $(L L R)$, it is good to express the weight in log form. Let $\sigma^{2}$ be the Gaussian noise variance of the channel. Then

$$
\begin{aligned}
\log w(e) & =\log \pi(u)+\log p(\boldsymbol{y} \mid \boldsymbol{x}) \\
& =\log \pi(u)-\frac{1}{2 \sigma^{2}}\|\boldsymbol{y}-\boldsymbol{x}\|^{2}-\log 2 \pi \sigma^{2} \\
& =\log \pi(u)-\frac{1}{2 \sigma^{2}}\left(y_{1}^{2}+x_{1}^{2}-2 x_{1} y_{1}+y_{2}^{2}+x_{2}^{2}-2 x_{2} y_{2}\right)-\log 2 \pi \sigma^{2}
\end{aligned}
$$

Since $x_{i} \in\{-1,+1\}, x_{i}^{2}$ is a constant. We can omit constants which are the same for $u=0$ and $u=1$. Thus we can define the logarithmic weight for $e \in E_{t, t+1}$ as

$$
\begin{equation*}
\tilde{w}(e)=\log \pi(u)+\frac{x_{1} y_{1}(t)+x_{2} y_{2}(t)}{\sigma^{2}} \tag{3}
\end{equation*}
$$

If $\pi(0)=\pi(1)=\frac{1}{2}$, we can further simplify (3) to

$$
\begin{equation*}
\tilde{w}(e)=\frac{x_{1} y_{1}(t)+x_{2} y_{2}(t)}{\sigma^{2}} \tag{4}
\end{equation*}
$$

4. $\alpha$ and $\beta$. The matrix $W_{i}$ used in the forward-backward algorithm is very sparse. To reduce the computational complexity, we should use (see [McEliece, 2001])

$$
\begin{aligned}
\alpha_{t}\left(s^{\prime}\right) & =\sum_{\substack{u=0,1 \\
e_{u}: s_{u} \mapsto s^{\prime} \in E_{t-1, t}}} \alpha_{t-1}\left(s_{u}\right) w\left(e_{u}\right), \\
\beta_{t}(s) & =\sum_{\substack{u=0,1 \\
e_{u}: s \mapsto s_{u}^{\prime} \in E_{t, t+1}}} \beta_{t+1}\left(s_{u}^{\prime}\right) w\left(e_{u}\right)
\end{aligned}
$$

The logarithmic version is

$$
\begin{align*}
\tilde{\alpha}_{t}\left(s^{\prime}\right) & =\log \left(e^{\tilde{\alpha}_{t-1}\left(s_{0}\right)+\tilde{w}\left(e_{0}\right)}+e^{\tilde{\alpha}_{t-1}\left(\boldsymbol{s}_{1}\right)+\tilde{w}\left(e_{1}\right)}\right)  \tag{5}\\
\tilde{\beta}_{t}(\boldsymbol{s}) & =\log \left(e^{\tilde{\beta}_{t+1}\left(s_{0}^{\prime}\right)+\tilde{w}\left(e_{0}\right)}+e^{\tilde{\beta}_{t+1}\left(\boldsymbol{s}_{1}^{\prime}\right)+\tilde{w}\left(e_{1}\right)}\right) \tag{6}
\end{align*}
$$

The initial values of $\tilde{\alpha}_{0}(\boldsymbol{s})$ and $\tilde{\beta}_{T}(\boldsymbol{s})$ are defined as follows:

$$
\tilde{\alpha}_{0}(s)=\tilde{\beta}_{T}(s)= \begin{cases}0, & s=\mathbf{0} \\ -\infty, & \text { otherwise }\end{cases}
$$

5. Log-likelihood Ratio. We have (assume $e=s \mapsto s^{\prime}$ )

$$
\begin{aligned}
& \log p(u(t)=0 \mid \mathcal{E})=\log \sum_{e \in E_{t-1, t}^{(0)}} \alpha_{t-1}(\boldsymbol{s}) w(e) \beta_{t}\left(\boldsymbol{s}^{\prime}\right)=\log \sum_{e \in E_{t-1, t}^{(0)}} e^{\tilde{\alpha}_{t-1}(\boldsymbol{s})+\tilde{w}(e)+\tilde{\beta}_{t}\left(\boldsymbol{s}^{\prime}\right)}, \\
& \log p(u(t)=1 \mid \mathcal{E})=\log \sum_{e \in E_{t-1, t}^{(1)}} \alpha_{t-1}(\boldsymbol{s}) w(e) \beta_{t}\left(\boldsymbol{s}^{\prime}\right)=\log \sum_{e \in E_{t-1, t}^{(1)}} e^{\tilde{\alpha}_{t-1}(\boldsymbol{s})+\tilde{w}(e)+\tilde{\beta}_{t}\left(\boldsymbol{s}^{\prime}\right)},
\end{aligned}
$$

and thus

$$
L L R_{t}=\log \frac{p(u(t)=0 \mid \mathcal{E})}{p(u(t)=1 \mid \mathcal{E})}=\log p(u(t)=0 \mid \mathcal{E})-\log p(u(t)=1 \mid \mathcal{E})
$$

6. Approximation of $\log \left(e^{x}+e^{y}\right)$. We are asked to use the logarithmic weights ((3) or (4)) to calculate $L L R$. This poses a problem with (5) and (6): how to calculate $\log \left(e^{x}+e^{y}\right)$ without doing log or exp. From Homework 2.2,

$$
\log \left(e^{x}+e^{y}\right)=\max \{x, y\}+f(|x-y|),
$$

where $f(\Delta)=\log \left(1+e^{-\Delta}\right)$. Here we approximate $f(\Delta)$. I tried:

- $f \equiv 0$. That is, use only $\max \{x, y\}$ to approximate $\log \left(e^{x}+e^{y}\right)$.
- 2-bit approximation. I tried two methods in my solution to Homework 2.2.

It turns out that the approximation in my solution 2.2(b) is the best among those three, and $f \equiv 0$ is almost as good as the approximation in the solution 2.2(a).
7. Histogram and normalization. We are asked to plot a histogram for $\left\{L L R_{t}\right\}_{t=0}^{k-1}$, or more precisely, the adjusted $L L R$, i.e., $\left\{u(t) \cdot L L R_{t}\right\}_{t=0}^{k-1}$. We do not care about the $L L R$ for the dummy bits.
If we divide the range of $L L R_{t}$ into $M$ bins, and count the number of $L L R_{t}$ 's in each bin, then we can plot the histogram. However, we can do better. We can make a probability density from the histogram if we do a normalization before plotting.
Assume all the bins have the same width, $w$. Denote the number of $L L R_{t}$ in bin $i$ by $c_{i}$. Then the probability density of $L L R_{t}$ in bin $i$ is

$$
p_{i}=\frac{c_{i}}{w \cdot k}
$$

since $p_{i}$ is proportional to $c_{i}$ and the 'integrate' of $p_{i}, \sum_{i} w p_{i}=1$. For $r$ runs (making the histogram of $L L R$ more accurate),

$$
p_{i}=\frac{c_{i}}{w \cdot k \cdot r}
$$

8. Random number generator. From [Press et al., 1992, Section 7.1], a linear congruential method for generating random numbers is not free of sequential correlation on successive calls. If the period is as small as 32768 , the number of lines on which pairs of points lie in 2D space will be no greater than $\sqrt{32768}$, or 181 . In this project, we will need about $10^{7}(\approx 2 T \times 5000$ runs $)$ random numbers. So I used the random number generator ran1() in [Press et al., 1992, Section 7.1]. However, my results from the computer tests didn't show much difference.
9. Basic results. The BCJR decoding algorithm was run 5000 times to determine the distribution of the adjusted $L L R$ and the average $B E R$ (bit error rate). These tests were performed for several different values of $E_{b} / N_{0}$. The results are shown in Figure 1.
If we conjecture that the distribution of the adjusted $L L R$ is Gaussian $\mathcal{N}\left(\ell, \sigma^{2}\right)$, we can calculate the $B E R$ from the Gaussian distribution as

$$
\begin{equation*}
B E R_{t}=\int_{-\infty}^{0} \frac{1}{\sqrt{2 \pi \sigma^{2}}} e^{-\frac{(x-\ell)^{2}}{2 \sigma^{2}}} d x=\frac{1}{\sqrt{\pi}} \int_{\ell / \sqrt{2 \sigma^{2}}}^{\infty} e^{-t^{2}} d t=\frac{1}{2} \operatorname{erfc}\left(\frac{\ell}{\sqrt{2 \sigma^{2}}}\right) \tag{7}
\end{equation*}
$$

where $\operatorname{erfc}(t)=\frac{2}{\sqrt{\pi}} \int_{t}^{\infty} e^{-t^{2}} d t$ can be calculated by $\operatorname{erfc}()$ in Matlab or $\operatorname{Erfc}[]$ in Mathematica. The mean $\ell$ and variance $\sigma^{2}$ can be statistically calculated from the adjusted $L L R$
data. Although Figure 1 (a) shows a good match of the real distribution of $L L R$ with the Gaussian approximation, Figure 1(b) implies that they two are not the same.
Below I list the average number of errors (in $k$ bits) over 5000 runs of the decoding, and $k \cdot B E R_{t}$, the number of errors from the corresponding Gaussian distribution.

| $E_{b} / N_{0}(\mathrm{~dB})$ | 6 | 5 | 4 | 3 | 2 | 1 |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |
| Actual error | 0.0010 | 0.0224 | 0.2458 | 1.8120 | 9.3418 | 34.4954 |
| Gaussian error | 0.000144 | 0.00519 | 0.1029 | 1.1990 | 8.9720 | 39.0258 |

10. Other interesting things.
(a) Random codeword. The codeword we used in the previous tests was generated by the recursion $u_{n+6}=u_{n+1} \oplus u_{n}$ with period 63 . I also tried randomly generated codewords. The results are similar.

| $E_{b} / N_{0}(\mathrm{~dB})$ | 6 | 5 | 4 | 3 | 2 | 1 |
| :---: | :--- | :--- | :--- | :---: | :---: | :---: |
| Actual error | 0.0014 | 0.0246 | 0.2410 | 1.7946 | 9.3622 | 34.1514 |
| Gaussian error | 0.000147 | 0.00522 | 0.0992 | 1.2054 | 8.9587 | 38.5913 |

(b) Unknown $\sigma^{2}$. One difference between the BCJR algorithm and the Viterbi algorithm is that we need to know the channel variance in the BCJR algorithm. We might wonder, if our guess of $\sigma^{2}$ is not the same as the real value of $\sigma^{2}$, how well the BCJR algorithm would perform. I tested the performance of the BCJR algorithm when our guess for $\sigma^{2}$ is $10^{0.1}$ larger than the real value, that is, our guess for $E_{b} / N_{0}$ is 1 dB below the true value. Figure 3 shows that (compared to Figure 2) the distribution of $L L R$ of $E_{b} / N_{0}=\lambda \mathrm{dB}$ seems to have the same mean and smaller variance as the distribution of $L L R$ of $E_{b} / N_{0}=(\lambda-1) \mathrm{dB}$ in Figure 2(a). However, the $B E R$ and $B E R_{t}$ changes little. (See table below.)

| $E_{b} / N_{0}(\mathrm{~dB})$ | 6 | 5 | 4 | 3 | 2 | 1 |
| :---: | :--- | :--- | :--- | :---: | :---: | :---: |
| Actual error | 0.0014 | 0.0248 | 0.2400 | 1.8032 | 9.4012 | 34.3674 |
| Gaussian error | 0.000142 | 0.00511 | 0.0994 | 1.2449 | 9.4592 | 40.6020 |

(c) Near-linear relationship. Notice that the mean and the variance of the adjusted $L L R$ both increase with $E_{b} / N_{0}$. It is interesting to find (Figure 4) a simple linear relationship between the mean and the variance of the adjusted $L L R$. However, a common feature of the points in Figure 4 is that points with smaller mean and larger mean have larger slope than points between them. My guess of the real variation vs. mean curve is that it is a little like tan - with bounds in both directions for the mean. We know that the mean of the adjusted $L L R$ should not be negative. I also guess that the upper bound for the mean is related to the free distance of the code.
(d) Other random number generators. I also tried some other random number generators, including the one with period 32768 . The resulting $B E R$ 's are similar to those got with ran1, though differences do exist. However, I did not test all those RNGs throughly.
(e) Asymmetry of $L L R$. We assumed that $L L R$ satisfies the Gaussian distribution. However, after careful observation of Figure $1(\mathrm{a})$ (of course, we need a larger plot. see Figure 5), the $L L R$ distribution is not symmetric. The left half-part is wider when $E_{b} / N_{0}$ is big, thus the $B E R$ calculated by (7) is smaller than the real one; when $E_{b} / N_{0}$ is small, the right half-part is wider thus the $B E R$ by the Gaussian is larger than the real one.More precisely, when $E_{b} / N_{0}$ is around 1.8 , the $L L R$ distribution is roughly symmetric. Now,


Figure 1: Result plots from 5000 runs of the BCJR decoding algorithm. ran1() in [Press et al., 1992] is used. (a) In each subplot, the blue curve outlines the distribution (histogram with 100 bins) of adjusted $L L R$ under corresponding $E_{b} / N_{0}$, and the red curve is the Gaussian distribution with mean and variance from the real $L L R$ data. (b) The blue circles give the average $B E R$ for 11 different tests. The red curve is the $B E R$ calculated by (7).


Figure 2: Result plots when the codeword is randomly generated. See Figure 1 for details.


Figure 3: Result plots when the codeword is randomly generated and the guess of $E_{b} / N_{0}$ is 1 dB lower that the true value. See Figure 1 for details.


Figure 4: Near-linear relationship between the mean and the variance of the adjusted $L L R$. Note that the lines are linear regressions of corresponding points.
from Figure $1(\mathrm{~b})$ we can see those two $B E R$ s coincide at $E_{b} / N_{0} \approx 1.8$. What's more, in Figure 4 , the variance is now twice of the mean.


Figure 5: The adjusted $L L R$ distribution is asymmetric ( $E_{b} / N_{0}=1 \mathrm{~dB}$, other conditions are same as Figure $1(\mathrm{a})$ ). The blue curve is the actual distribution of $L L R$, and the red curve is the reflection of the blue one about the mean. The black dashed curve is the Gaussian distribution with the same mean and variance.

## References

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